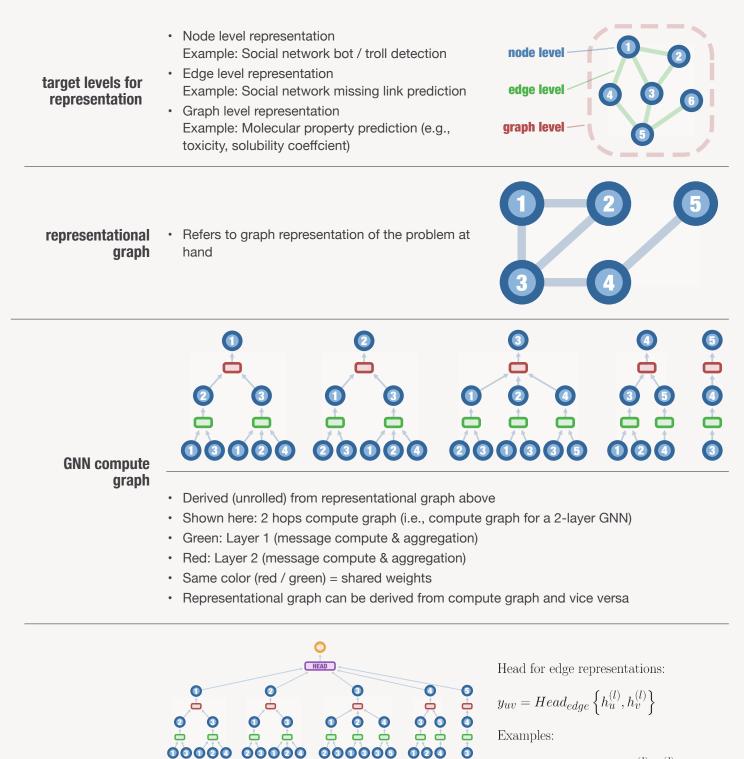
## **Cheatsheet: GNNs**

Graph Neural Networks and Transformers: Neural Networks for Sets



$$\begin{aligned} y_{uv} &= Linear(Concat(h_{u}^{(l)}, h_{v}^{(l)})) \\ y_{uv} &= h_{u}^{(l)} + h_{v}(l) \\ y_{uv} &= dot(h_{u}^{(l)}, h_{v}^{(l)}) \end{aligned}$$

Head for graph representations:

$$y_G = Head_{graph}\left\{(h_v^{(l)}) \in R^d, \forall v \in G)\right\}$$

getting to the target level

- In most cases, core GNNs produce node-level representations
- Edge-level representation: aggregating representations of adjacent nodes
- Graph-level representation: aggregating
   representations of all nodes in the graph
- Example above: graph level task















 Node features get transformed by a function MSG(), typically a neural network (MLP)

message computation

- Input: fixed-length feature vector (concatenation or sum of multiple embeddings)
- Output: Message (fixed-length vector)
- Function is applied to each input vector individually

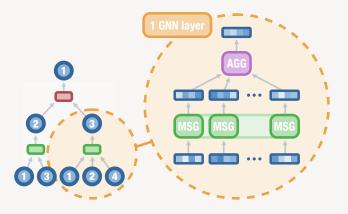
aggregated into a single vector

• Multiple messages get

by a function AGG()Input: N messages

· Output: Fixed-length vector

invariance (no concatenation!)
Examples: Sum(), Mean(), Max()
Optimal: MLP(Sum(message)) with message = MLP(feature)



One GNN layer:

$$\begin{split} h_v^{(l)} &= AGG^{(l)}\left(\left\{MSG^{(l)}\left(h_u^{(l-1)}\right), u \in N(v)\right\}\right)\\ \text{Alternatives for } MSG\left(\cdot\right): \end{split}$$

$$\begin{split} MSG^{(l)} \begin{pmatrix} h_u^{(l-1)} \\ h_u^{(l-1)} \end{pmatrix} &= m_u^{(l)} = W^{(l)} h_u^{(l-1)} \\ MSG^{(l)} \begin{pmatrix} h_u^{(l-1)} \\ h_u^{(l-1)} \end{pmatrix} &= m_u^{(l)} = MLP(h_u^{(l-1)}) \end{split}$$

Alternatives for  $AGG(\cdot)$ :

$$\begin{split} &AGG^{(l)}\left(\left\{m_u^{(l)}, u \in N(v)\right\}\right) = Sum\left(\left\{m_u^{(l)}, u \in N(v)\right\}\right) = \sum_{u \in N(v)} m_u^{(l)} \\ &AGG^{(l)}\left(\cdot\right) = Mean\left(\cdot\right) \\ &AGG^{(l)}\left(\cdot\right) = Max\left(\cdot\right) \\ &AGG^{(l)}\left(\cdot\right) = MLP\left(Sum\left(\cdot\right)\right) \end{split}$$

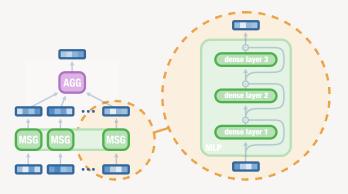
Optional extensions:

$$\begin{split} h_v^{(l)} &\leftarrow AGG^{(l)}\left(\left\{MSG^{(l)}\left(h_u^{(l-1)}\right), u \in N(v)\right\}\right) \\ h_v^{(l)} &\leftarrow CONCAT\left(h_v^{(l)}, MSG_t^{(l)}\left(h_v^{(l-1)}\right)\right) \\ h_v^{(l)} &\leftarrow \sigma\left(W^l \cdot h_v^{(l)}\right) \\ h_v^{(l)} &\leftarrow \frac{h_v^{(l)}}{\|h_v^{(l)}\|_2} \end{split}$$

- Each GNN-layer increases "receptive field" by one hop
- GNNs typically have 2-3 layers
   (more is often not helpful)
- Instead:

layer connectivity

- Increase the size / number of layers of the networks within the GNN-layers
- Pre-process raw features with deep networks
- Add skip-connections

















aggregation (typically of same size) • Requirement: Permutation